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# 1 Radix-4 decimate in time complex FFT

## 1.1 Description

This function computes a complex FFT from an input signal. It uses the Radix-4 “Decimate In Time” algorithm and does not perform a calculation “in place” which means that the input buffer has to be different from the output buffer.

### 1.1.1 Function prototype

```
void dspXX_trans_complexfft(  
    dspXX_complex_t *vect1,  
    dspXX_t *vect2,  
    int nlog);
```

where XX corresponds to the number of bits of a basic data element (i.e. 16 or 32).

### 1.1.2 Arguments

This function takes three parameters: the output buffer, the input buffer and a value corresponding to the size of those buffers.

- The output buffer (vect1) is a pointer on a complex vector of  $2^{nlog}$  elements.
- The input buffer (vect2) is a pointer on a real vector of  $2^{nlog}$  elements.
- The size argument (nlog) is in fact the base-2-logarithm of the size of the input vector. ( $nlog \in [2, 4, 6, \dots, 28]$ )

### 1.1.3 Algorithm

Following is the algorithm used to implement the radix-4 DIT complex FFT. The optimized version is based on this algorithm but can differ in certain points due to the instruction set of the target:

```
size = 1 << nlog
```

```
FOR r FROM 0 TO size-1 STEP 4 DO  
    Butterfly_zero_only_real_and_bit_reversing(vect1, vect2, r)  
END
```

```
FOR stage FROM 1 TO nlog/2 DO  
    m = 4 ^ stage
```

```
    FOR r FROM 0 TO size-1 STEP m DO  
        Butterfly_zero(vect1, r)  
    END
```

```
    FOR j FROM 1 TO m / 4 - 1 DO  
        Comput_twiddle_factors(e, e2, e3, j / m)
```

```
        FOR r FROM 0 TO size-1 STEP m DO  
            Butterfly(vect1, r, j, e, e2, e3)  
        END
```

```
    END
```

```
END
```

### 1.1.4 Notes

- **Interruptibility:** the code is interruptible.
- In-place computation is not allowed.
- This function uses a static twiddle factors table raw-coded in the file “*BASIC/TRANSFORMS/dspXX\_twiddle\_factors.h*”. To generate those factors, you can use the script called “*tf\_gen.sci*” and execute it with Scilab.
- To avoid overflowing values, the resulting vector amplitude is scaled by  $2^{\wedge}nlog$ .
- All the vectors have to be 32-bit aligned.

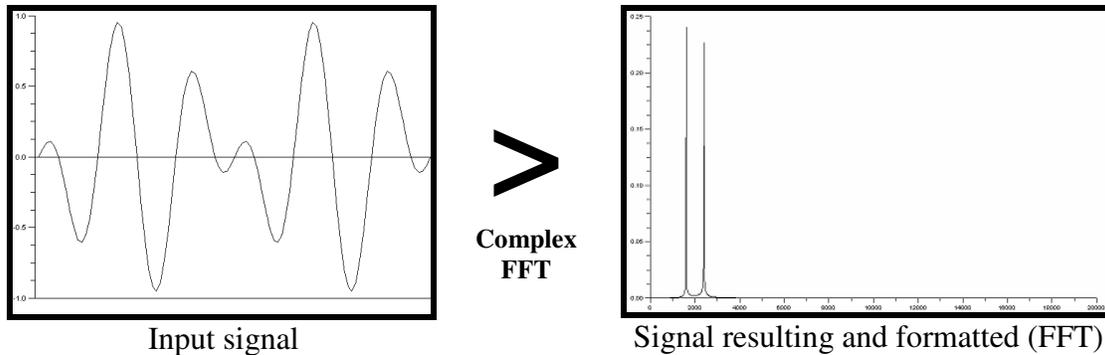
## 1.2 Benchmark

### 1.2.1 Benchmark routine

All these functions have been benchmarked on an avr32-uc3a0512 target. The programs have been compiled with avr32-gcc (4.0.2-atmel.1.0.0) with the -O3 optimization option and have been stored in FLASH memory. The fixed-point format used is the Q1.15 format for the 16-bit data and the Q1.31 format for the 32-bit data.

The benchmark process has been performed with the same input signal for all those functions and compared with a reference’s signal computed with a mathematic tool using floating point.

The input signal is a combination of one sine and one cosine. The sine oscillating at 400Hz and the cosine at 2KHz. Those signals have been multiplied and sampled at 40KHz.



### 1.2.2 Result

Here are tables of the main values of the benchmark results. All those values correspond to the best performances of the functions and are obtained with different compilation options. For more information, please refer to the complete benchmark result table in annexes.

### 1.2.2.1 16-bit radix-4 D.I.T. complex FFT: generic

Concerned file path: /BASIC/TRANSFORMS/dsp16\_complex\_fft\_generic.c

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error		Lowest Algorithm's size in memory
			Amplitude average	Max. amplitude	
<b>64-points</b>	6,296	108.2us	1.58e-5	6.53e-5	1.1 Kbytes
<b>256-points</b>	33,723	578.0us	1.69e-5	8.80e-5	1.3 Kbytes
<b>1024-points</b>	169,006	2.90ms	1.67e-5	12.31e-4	2.0 Kbytes
<b>4096-points</b>	812,321	13.90ms	1.52e-5	14.60e-4	5.0 Kbytes

*More details on Table 1.1.1 in annexes*

### 1.2.2.2 16-bit radix-4 D.I.T. complex FFT: avr32-uc3 optimized

Concerned file path: /BASIC/TRANSFORMS/dsp16\_complex\_fft\_avr32uc3.c

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error		Lowest Algorithm's size in memory
			Amplitude average	Max. amplitude	
<b>64-points</b>	2,611	44.4 us	1.63e-5	6.53e-5	710 bytes
<b>256-points</b>	13,661	232.2 us	1.68e-5	7.46e-5	902 bytes
<b>1024-points</b>	67,671	1.15 ms	1.69e-5	1.02e-4	1.6 Kbytes
<b>4096-points</b>	322,897	5.49 ms	1.58e-5	1.18e-4	4.6 Kbytes

**Warning: this function is only compatible with Q1.15 numbers.**

Note: this function needs 72 bytes of memory for the stack.

*More details on Table 1.1.2 in annexes*

### 1.2.2.3 32-bit radix-4 D.I.T. complex FFT: generic

Concerned file path: /BASIC/TRANSFORMS/dsp32\_complex\_fft\_generic.c

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error		Lowest Algorithm's size in memory
			Amplitude average	Max. amplitude	
<b>64-points</b>	13,206	225.2us	6.0e-10	5.7e-9	2.0 Kbytes
<b>256-points</b>	74,297	1.27us	3.0e-10	4.8e-9	2.4 Kbytes
<b>1024-points</b>	383,212	6.53ms	3.0e-10	6.1e-9	3.9 Kbytes

*More details on Table 1.2.1 in annexes*

## 2 Convolution

### 2.1 Description

This function performs a linear convolution between two discrete sequences.

#### 2.1.1 Function prototype

```
void dspXX_vect_conv(
    dspXX_t *vect1,
    dspXX_t *vect2,
    int vect2_size,
    dspXX_t *vect3,
    int vect3_size);
```

where *XX* corresponds to the number of bits of a basic data element (i.e. 16 or 32).

#### 2.1.2 Arguments

This function takes five parameters: the output buffer, the two discrete sequences and their respective sizes.

- The output buffer (*vect1*) is a pointer on a real vector of (**vect2\_size + vect3\_size - 1**) elements.
- The first input buffer (*vect2*) is a pointer on a real vector of **vect2\_size** elements.
- The first size argument (*vect2\_size*) is the length of the first input buffer ( $\text{vect2\_size} \in [8, 9, 10, \dots]$ ).
- The second input buffer (*vect3*) is a pointer on a real vector of **vect3\_size** elements.
- The second size argument (*vect3\_size*) is the length of the second input buffer ( $\text{vect3\_size} \in [8, 9, 10, \dots]$ ).

#### 2.1.3 Requirements

This function requires 3 modules:

Module name	Function name	Concerned file path
Zero Padding	dspXX_vect_zeropad	/BASIC/VECTORS/zero_padding.c
Copy	dspXX_vect_copy	/BASIC/VECTORS/copy.c
Partial Convolution	dspXX_vect_convpart	/BASIC/VECTORS/convolution_partial.c



The output buffer of the function has to have at least a length of  $N + 2 * M - 2$  elements because of intern computations, where *N* is the length of the largest input buffer and *M*, the length of the smallest input buffer.

#### 2.1.4 Algorithm

Following is the algorithm used to implement the convolution product. The optimized version is based on this algorithm but can differ in certain points due to the instruction set of the target:

```

IF vect2_size >= vect3_size THEN
    vect1 = 

|                       |                   |                       |
|-----------------------|-------------------|-----------------------|
| 0 0 0 0 ... 0 0 0 0   | vect2             | 0 0 0 0 ... 0 0 0 0   |
| <i>vect3_size - 1</i> | <i>vect2_size</i> | <i>vect3_size - 1</i> |

Partial_convolution(vect1, vect1, vect2_size + 2*(vect3_size - 1), vect3, vect3_size)
ELSE
    vect1 = 

|                       |                   |                       |
|-----------------------|-------------------|-----------------------|
| 0 0 0 0 ... 0 0 0 0   | vect3             | 0 0 0 0 ... 0 0 0 0   |
| <i>vect2_size - 1</i> | <i>vect3_size</i> | <i>vect2_size - 1</i> |

Partial_convolution(vect1, vect1, vect3_size + 2*(vect2_size - 1), vect2, vect2_size)
END

```

## 2.1.5 Notes

- **Interruptibility:** the code is interruptible.
- Due to its implementation, the dsp16-avr32-uc3 optimized version of the FIR requires a length of 4\*m elements for the largest input discrete sequence and the output buffer (vect1) has to have a length of 4\*n elements to avoid overflows.
- The input discrete sequences have to be scaled to avoid overflowing values.
- All the vectors have to be 32-bit aligned.

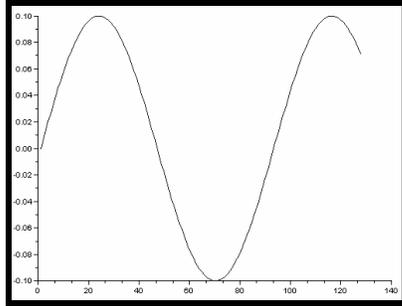
## 2.2 Benchmark

### 2.2.1 Benchmark routine

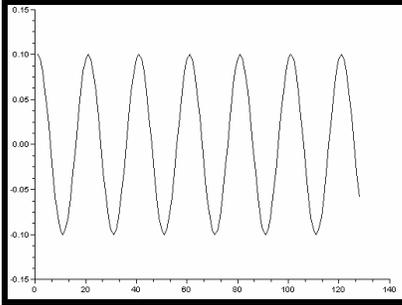
All these functions have been benchmarked on an avr32-uc3a0512 target. The programs have been compiled with avr32-gcc (4.1.2-atmel.1.0.0) with the -O3 optimization option and have been stored in FLASH memory. The fixed-point format used is the Q1.15 format for the 16-bit data and the Q1.31 format for the 32-bit data.

The benchmark process has been performed with the same input signal and impulse response for all those functions and compared with a reference's signal computed with a mathematic tool using floating point.

The first input signal is a sine oscillating at 433Hz and the second input signal is a cosine oscillating at 2KHz. Those signals are sampled at 40KHz.

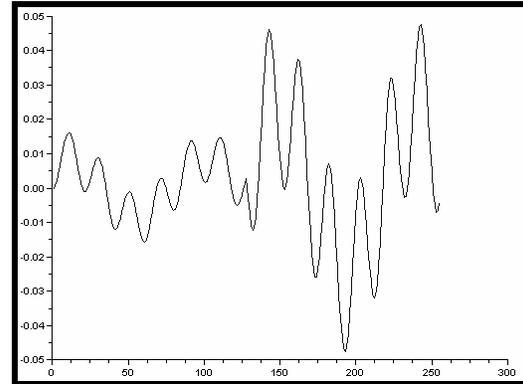


1<sup>st</sup> input signal



2<sup>nd</sup> input signal

>  
FIR filter



Resulting signal

## 2.2.2 Result

Here are tables of the main values of the benchmark results. All those values correspond to the best performances of the functions and are obtained with different compilation options. For more information, please refer to the complete benchmark result table in annexes.

Concerned file path: `/BASIC/VECTORS/convolution.c`

### 2.2.2.1 16-bit Convolution: generic

Algorithm's size in memory: 2.2 Kbytes.

Length of the first input signal: 64 elements.

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>32-points</b>	23,524	408.5us	2.0e-5	4.5e-5
<b>64-points</b>	57,757	1.00ms	1.8e-5	4.7e-5
<b>128-points</b>	86,752	1.50ms	1.8e-5	4.4e-5
<b>256-points</b>	144,736	2.51ms	1.5e-5	4.8e-5

*More details on Table 2.1.1 in annexes*

### 2.2.2.2 16-bit Convolution: avr32-uc3 optimized

Algorithm's size in memory: 950 bytes.

Length of the first input signal: 64 elements.

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>32-points</b>	8,248	151.2us	2.0e-5	4.5e-5
<b>64-points</b>	19,087	349.1us	1.8e-5	4.7e-5
<b>128-points</b>	28,532	521.8us	1.8e-5	4.4e-5
<b>256-points</b>	47,412	866.9us	1.5e-5	4.8e-5

*More details on Table 2.1.2 in annexes*

### 2.2.2.3 32-bit Convolution: generic

Algorithm's size in memory: 3.3 Kbytes.

Length of the first input signal: 64 elements.

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>32-points</b>	42,572	729.8us	0.4e-9	2.1e-9
<b>64-points</b>	109,179	1.87ms	0.4e-9	1.7e-9
<b>128-points</b>	163,968	2.81ms	0.5e-9	1.6e-9
<b>256-points</b>	273,536	4.69ms	0.6e-9	2.7e-9

*More details on Table 2.2.1 in annexes*

### 2.2.2.4 32-bit Convolution: avr32-uc3 optimized

Algorithm's size in memory: 1.5 Kbytes.

Length of the first input signal: 64 elements.

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>32-points</b>	19,958	340.2us	0.5e-9	2.1e-9
<b>64-points</b>	50,501	860.4us	0.5e-9	1.7e-9
<b>128-points</b>	75,722	1.29ms	0.6e-9	2.4e-9
<b>256-points</b>	126,154	2.15ms	0.7e-9	2.7e-9

*More details on Table 2.2.2 in annexes*

## 3 FIR Filter (*alias Partial Convolution*)

### 3.1 Description

This function computes a real FIR filter using the impulse response of the desired filter onto a fixed-length signal.

#### 3.1.1 Function prototype

```
void dspXX_filt_fir(
    dspXX_t *vect1,
    dspXX_t *vect2,
    int size,
    dspXX_t *h,
    int h_size);
void dspXX_vect_convpart(
    dspXX_t *vect1,
    dspXX_t *vect2,
    int vect2_size,
    dspXX_t *vect3,
    int vect3_size);
```

where XX corresponds to the number of bits of a basic data element (i.e. 16 or 32).

#### 3.1.2 Arguments

This function takes five parameters: the output buffer, the input buffer, its size, the impulse response of the filter and its size.

- The output buffer (vect1) is a pointer on a real vector of (**size - h\_size + 1**) elements.
- The input buffer (vect2) is a pointer on a real vector of **size** elements.
- The size argument (size) is the length of the input buffer (size ∈ [4, 8, 12, ...]).
- The impulse response of the filter (h) is a pointer on a real vector of **h\_size** elements.
- The size argument (h\_size) is the length of the impulse response of the filter (h\_size ∈ [8, 9, 10, ...]).

#### 3.1.3 Requirements

This function requires one module:

Module name	Function name	Concerned file path
Partial Convolution	dspXX_vect_convpart	/BASIC/VECTORS/convolution_partial.c

#### 3.1.4 Algorithm

Following is the algorithm used to implement the FIR filter. The optimized version is based on this algorithm but can differ in certain points due to the instruction set of the target:

```
FOR j FROM 0 TO size - h_size + 1 DO
    sum = 0

    FOR i FROM 0 TO h_size DO
        sum += vect2[i] * h[h_size - i - 1]
    END

    vect1[j] = sum >> DSPXX_QB
END
```

### 3.1.5 Notes

- **Interruptibility:** the code is interruptible.
- Due to its implementation, for the dsp16-avr32-uc3 optimized version of the FIR, the output buffer (vect1) has to have a length of  $4*n$  elements to avoid overflows.
- The impulse response of the filter has to be scaled to avoid overflowing values.
- All the vectors have to be 32-bit aligned.

## 3.2 Benchmark

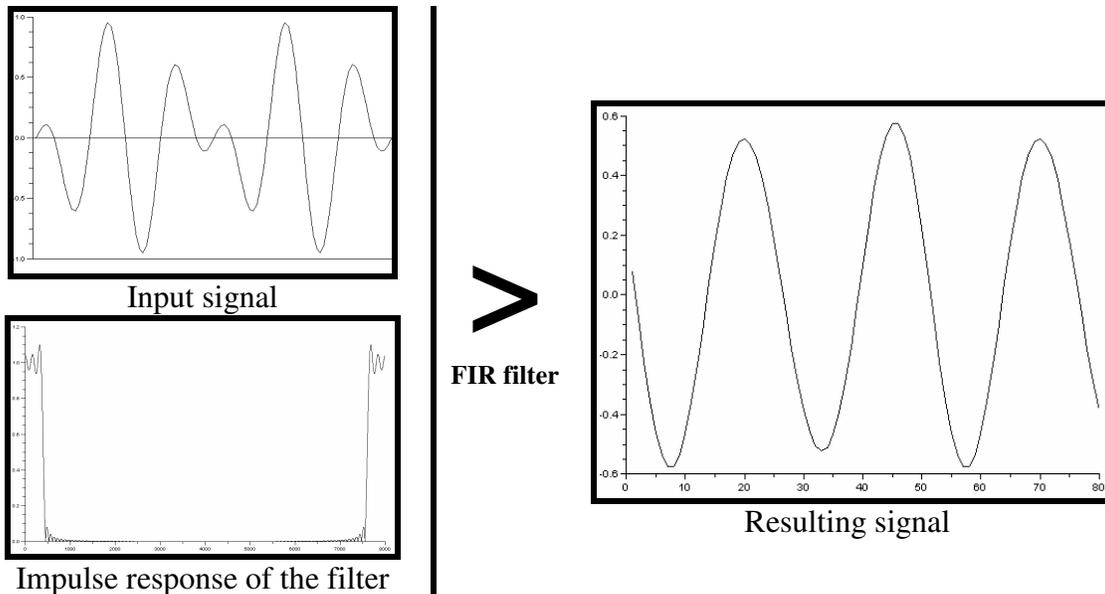
### 3.2.1 Benchmark routine

All these functions have been benchmarked on an avr32-uc3a0512 target. The programs have been compiled with avr32-gcc (4.1.2-atmel.1.0.0) with the `-O3` optimization option and have been stored in FLASH memory. The fixed-point format used is the Q1.15 format for the 16-bit data and the Q1.31 format for the 32-bit data.

The benchmark process has been performed with the same input signal and impulse response for all those functions and compared with a reference's signal computed with a mathematic tool using floating point.

The input signal is a combination of one sine and one cosine. The sine oscillating at 400Hz and the cosine at 2KHz. Those signals have been multiplied and sampled at 40KHz.

The impulse response describes a low-pass filter with a cutoff frequency equal to 400Hz.



### 3.2.2 Result

Here are tables of the main values of the benchmark results. All those values correspond to the best performances of the functions and are obtained with different compilation options. For more information, please refer to the complete benchmark result table in annexes.

### 3.2.2.1 16-bit FIR filter: generic

Concerned file path: `/BASIC/VECTORS/dsp16_convpart_generic.c`

Algorithm's size in memory: 2.0 Kbytes.

Number of Taps: 24.

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>64-points</b>	7,424	128.0us	2.27e-5	9.46e-5
<b>256-points</b>	41,793	720.0us	2.22e-5	9.46e-5
<b>512-points</b>	87,617	1.51ms	2.23e-5	9.46e-5
<b>1024-points</b>	179,265	3.09ms	2.21e-5	9.46e-5

*More details on Table 3.1.1 in annexes*

### 3.2.2.2 16-bit FIR filter: avr32-uc3 optimized

Concerned file path: `/BASIC/VECTORS/dsp16_convpart_avr32uc3.c`

Algorithm's size in memory: 770 bytes.

Number of Taps: 24.

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>64-points</b>	2,439	44.3us	2.27e-5	9.46e-5
<b>256-points</b>	12,712	230.7us	2.22e-5	9.46e-5
<b>512-points</b>	26,408	479.2us	2.23e-5	9.46e-5
<b>1024-points</b>	53,800	976.3us	2.21e-5	9.46e-5

*More details on Table 3.1.2 in annexes*

### 3.2.2.3 32-bit FIR filter: generic

Concerned file path: `/BASIC/VECTORS/dsp32_convpart_generic.c`

Algorithm's size in memory: 3.1 Kbytes.

Number of Taps: 24.

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>64-points</b>	13,984	239.4us	2.1e-9	1.24e-8
<b>256-points</b>	79,073	1.35ms	2.3e-9	1.74e-8
<b>512-points</b>	165,857	2.84ms	2.6e-9	2.31e-8
<b>1024-points</b>	339,425	5.81ms	3.7e-9	2.84e-8

*More details on Table 3.2.1 in annexes*

### 3.2.2.4 32-bit FIR filter: avr32-uc3 optimized

Concerned file path: /BASIC/VECTORS/dsp32\_convpart\_avr32uc3.c

Algorithm's size in memory: 1.3 Kbytes.

Number of Taps: 24.

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>64-points</b>	6,479	110.2us	2.1e-9	1.24e-8
<b>256-points</b>	36,432	619.0us	2.3e-9	1.24e-8
<b>512-points</b>	76,368	1.30ms	2.6e-9	2.31e-8
<b>1024-points</b>	156,240	2.65ms	3.7e-9	2.84e-8

*More details on Table 3.2.2 in annexes*

## 4 IIR Filter

### 4.1 Description

This function computes a real IIR filter using the impulse response of the desired filter onto a fixed-length signal.

#### 4.1.1 Function prototype

```
void dspXX_filt_iir(  
    dspXX_t *vect1,  
    dspXX_t *vect2,  
    int size,  
    dspXX_t *num,  
    int num_size,  
    dspXX_t *den,  
    int den_size,  
    int prediv);
```

where *XX* corresponds to the number of bits of a basic data element (i.e. 16 or 32).

#### 4.1.2 Arguments

This function takes five parameters: the output buffer, the input buffer, its size, the coefficients of the filter, their sizes and a coefficient's predivisor.

- The output buffer (*vect1*) is a pointer on a real vector of (**size - num\_size + 1**) elements.
- The input buffer (*vect2*) is a pointer on a real vector of **size** elements.
- The size argument (*size*) is the length of the input buffer ( $size \in [4, 5, 6, 7, \dots]$ ).
- The numerator's coefficients argument of the filter (*num*) is a pointer on a real vector of **num\_size** elements.
- The size argument (*num\_size*) is the length of the numerator's coefficients of the filter ( $num\_size \in [1, 2, 3, \dots]$ ).
- The denominator's coefficients argument of the filter (*den*) is a pointer on a real vector of **den\_size** elements.
- The size argument (*den\_size*) is the length of the denominator's coefficients of the filter ( $den\_size \in [1, 2, 3, \dots]$ ).
- The predivisor (*prediv*) is used to scale down the denominator's coefficients of the filter in order to avoid overflow values. So when you use this feature, you have to prescale manually the denominator's coefficients by  $2^{\text{prediv}}$  else leave this field to 0.

#### 4.1.3 Algorithm

Following is the algorithm used to implement the IIR filter. The optimized version is based on this algorithm but can differ in certain points due to the instruction set of the target:

```
// Initialization of the vect1 coefficients
FOR n FROM 0 TO den_size - 1 DO
    sum1 = 0
    FOR m FROM 0 TO num_size - 1 DO
        sum1 += num[m] * vect2[n + num_size - m - 1]
    END

    sum2 = 0
    FOR m FROM 1 TO n DO
        sum2 += den[m] * vect1[n - m]
    END

    vect1[n] = (sum1 - (sum2 << prediv)) >> DSPXX_QB
END

FOR n FROM n TO size - num_size DO
    sum1 = 0
    FOR m FROM 0 TO num_size - 1 DO
        sum1 += num[m] * vect2[n + num_size - m - 1]
    END

    sum2 = 0
    FOR m FROM 1 TO den_size - 1 DO
        sum2 += den[m] * vect1[n - m]
    END

    vect1[n] = (sum1 - (sum2 << prediv)) >> DSPXX_QB
END
```

#### 4.1.4 Notes

- **Interruptibility:** the code is interruptible.
- Due to its implementation, for the dsp16-avr32-uc3 optimized version of the FIR, the output buffer (vect1) has to have a length of  $4*n$  elements to avoid overflows.
- The impulse response of the filter has to be scaled to avoid overflowing values.
- All the vectors have to be 32-bit aligned.
- The first denominator's coefficient have to be equal to  $1 / (2^{\text{prediv}})$ .
- The predivisor (prediv) must be lower or equals to the constant DSPXX\_QB.

## 4.2 Benchmark

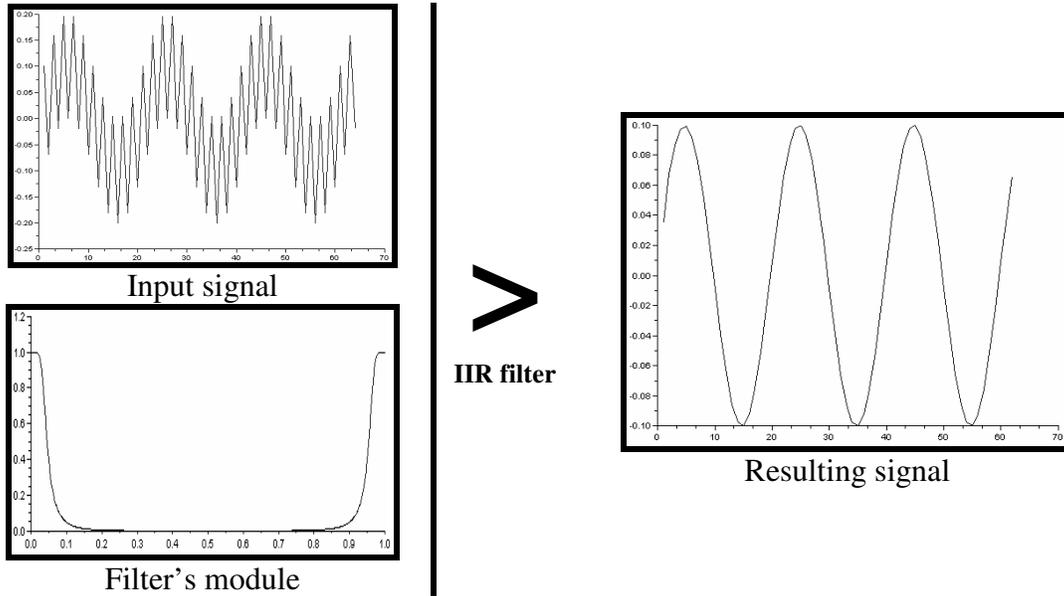
### 4.2.1 Benchmark routine

All these functions have been benchmarked on an avr32-uc3a0512 target. The programs have been compiled with avr32-gcc (4.1.2-atmel.1.0.0) with the -O3 optimization option and have been stored in FLASH memory. The fixed-point format used is the Q1.15 format for the 16-bit data and the Q1.31 format for the 32-bit data.

The benchmark process has been performed with the same input signal and impulse response for all those functions and compared with a reference's signal computed with a mathematic tool using floating point.

The input signal is a combination of one sine and one cosine. The sine oscillating at 400Hz and the cosine at 4KHz. Those signals have been added together and sampled at 8KHz.

The filter used is a low-pass Butterworth filter with a cutoff frequency equal to 2KHz.



### 4.2.2 Result

Here are tables of the main values of the benchmark results. All those values correspond to the best performances of the functions and are obtained with different compilation options. For more information, please refer to the complete benchmark result table in annexes.

#### 4.2.2.1 16-bit IIR filter: generic

Concerned file path: `/BASIC/FILTERING/dsp16_iir_generic.c`

Algorithm's size in memory: 266 bytes.

Order of the filter: 7

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>72-points</b>	11,469	213.4us	1.40e-5	4.30e-5
<b>256-points</b>	44,591	829.8us	1.40e-5	4.30e-5
<b>512-points</b>	90,671	1.69ms	1.40e-5	4.30e-5
<b>1024-points</b>	182,831	3.40ms	1.40e-5	4.30e-5

*More details on Table 4.1.1 in annexes*

#### 4.2.2.2 16-bit IIR filter: avr32-uc3 optimized

Concerned file path: /BASIC/FILTERING/dsp16\_iir\_avr32uc3.c

Algorithm's size in memory: 1.0 Kbytes (size optimization), 3.1 Kbytes (speed optimization).

Order of the filter: 7

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>72-points</b>	4,332	78.0us	1.90e-5	6.90e-5
<b>256-points</b>	15,006	270.5us	1.70e-5	6.90e-5
<b>512-points</b>	29,854	538.2us	1.70e-5	6.90e-5
<b>1024-points</b>	59,550	1.07ms	1.70e-5	6.90e-5

*More details on Table 4.1.2 in annexes*

#### 4.2.2.3 32-bit IIR filter: generic

Concerned file path: /BASIC/FILTERING/dsp32\_iir\_generic.c

Algorithm's size in memory: 400 bytes.

Order of the filter: 7

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>72-points</b>	14,517	265.4us	1.50e-9	7.00e-9
<b>256-points</b>	56,471	1.03ms	1.50e-9	7.00e-9
<b>512-points</b>	114,839	2.10ms	1.50e-9	7.00e-9
<b>1024-points</b>	231,575	4.23ms	1.50e-9	7.00e-9

*More details on Table 4.2.1 in annexes*

#### 4.2.2.4 32-bit IIR filter: avr32-uc3 optimized

Concerned file path: /BASIC/FILTERING/dsp32\_iir\_avr32uc3.c

Algorithm's size in memory: 3.0 Kbytes.

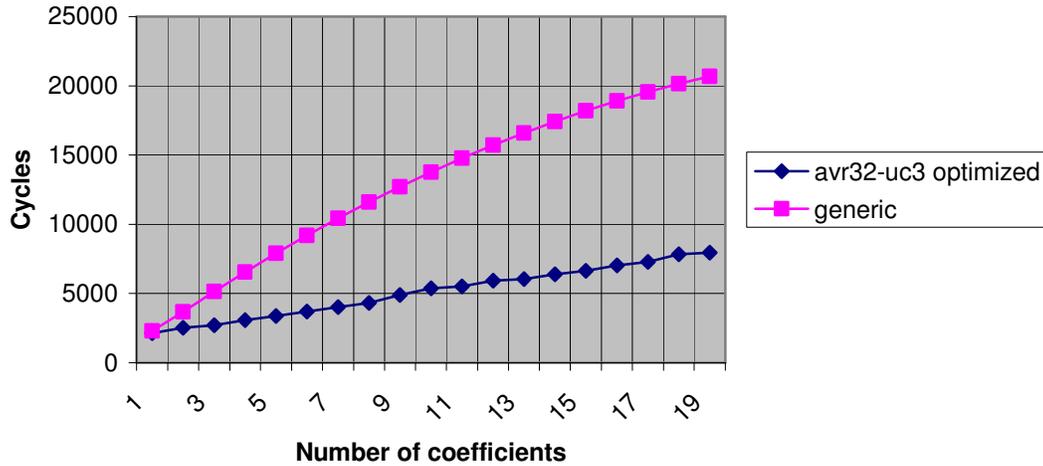
Order of the filter: 7

	Lowest cycle count	Fastest computation at 60 MHz	Lowest Error	
			Amplitude average	Max. amplitude
<b>72-points</b>	8,859	153.9us	1.50e-9	7.00e-9
<b>256-points</b>	33,333	577.1us	1.50e-9	7.00e-9
<b>512-points</b>	67,381	1.17ms	1.60e-9	7.00e-9
<b>1024-points</b>	135,477	2.34ms	1.60e-9	7.00e-9

*More details on Table 4.2.2 in annexes*

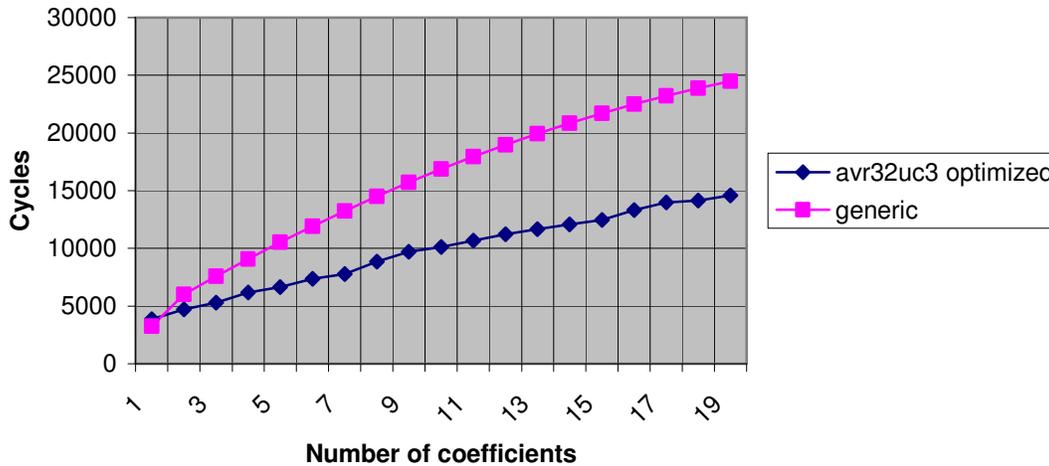
**Benchmark results for the 16-bit version (with speed optimization)**

The benchmark has been performed on a 72-element input signal.



**Benchmark results for the 32-bit version (with speed optimization)**

The benchmark has been performed on a 72-element input signal.



Remark: the number of coefficients corresponds to a filter which order is equal to "Number of coefficients" - 1.

## 5 Annexes

TABLE 1.1.1 - BENCHMARK OF 16-BIT RADIX-4 D.I.T. COMPLEX FFT: GENERIC

	Optimization	T.F.T.* in SRAM (cycles)		T.F.T.* in FLASH (cycles)		Error		Algorithm's size in memory (bytes) (code size + T.F.T.* size)
		wait-state		wait-state		Amplitude average ( $\times 10^{-5}$ )	Max. amplitude ( $\times 10^{-5}$ )	
		0 at 30MHz	1 at 60MHz	0 at 30MHz	1 at 60MHz			
64-point	(0)	<b>6,296</b> (209.9us)	6,489 ( <b>108.2us</b> )	6,640 (221.3us)	7,012 (116.9us)	2.98	15.63	1K (840 + 194)
	(1)	6,343 (211.4us)	6,538 (109.0us)	6,777 (225.9us)	7,167 (119.5us)	<b>1.58</b>	<b>6.53</b>	1K (844 + 194)
	(2)	6,666 (222.2us)	6,959 (116.0us)	7,092 (236.4us)	7,546 (125.8us)	2.98	15.63	<b>1.1K</b> (1032 + 66)
	(3)	6,747 (224.9us)	6,996 (116.6us)	7,101 (236.7us)	7,536 (125.6us)	1.58	6.53	1K (984 + 66)
256-point	(0)	<b>33,723</b> (1124.1us)	34,682 ( <b>578.0us</b> )	35,265 (1175.5us)	37,033 (617.2us)	3.02	21.92	1.6K (840 + 770)
	(1)	34,041 (1134.7us)	35,003 (583.4us)	35,988 (1199.6us)	37,836 (630.6us)	<b>1.69</b>	<b>8.80</b>	1.6K (844 + 770)
	(2)	35,304 (1176.8us)	36,675 (611.3us)	37,194 (1239.8us)	39,294 (654.9us)	3.02	21.92	<b>1.3K</b> (1032 + 258)
	(3)	35,826 (1194.2us)	37,032 (617.2us)	37,419 (1247.3us)	39,453 (657.6us)	1.69	8.80	1.2K (984 + 258)
1024-point	(0)	<b>169,006</b> (5.63ms)	173,611 ( <b>2.90ms</b> )	175,394 (5.85ms)	183,358 (3.06ms)	3.04	25.01	3.8K (840 + 3K)
	(1)	170,795 (5.69ms)	175,404 (2.92ms)	178,863 (5.96ms)	187,161 (3.12ms)	<b>1.67</b>	<b>12.31</b>	3.8K (844 + 3K)
	(2)	175,446 (5.85ms)	181,703 (3.03ms)	183,248 (6.11ms)	192,530 (3.21ms)	3.04	25.01	<b>2K</b> (1032 + 1K)
	(3)	178,153 (5.94ms)	183,772 (3.06ms)	184,761 (6.16ms)	193,802 (3.23ms)	1.67	12.31	2K (984 + 1K)
4096-point	(0)	<b>812,321</b> (27.08ms)	833,820 ( <b>13.90ms</b> )	838,147 (27.94ms)	873,235 (14.55ms)	3.09	32.90	12.8K (840 + 12K)
	(1)	821,533 (27.38ms)	843,037 (14.05ms)	854,154 (28.47ms)	890,598 (14.84ms)	<b>1.52</b>	<b>14.60</b>	12.8K (844 + 12K)
	(2)	838,212 (27.94ms)	866,315 (14.44ms)	869,718 (28.99ms)	910,054 (15.17ms)	3.09	32.90	<b>5K</b> (1032 + 4K)
	(3)	851,232 (28.37ms)	876,816 (14.61ms)	877,959 (29.27ms)	917,367 (15.29ms)	1.52	14.60	5K (984 + 4K)

\*: Twiddle Factors Table.

(0): Algorithmic optimized for **speed**.

(1): Algorithmic optimized for **accuracy**.

(2): Algorithmic optimized for **size**.

(3): Algorithmic optimized for **size and accuracy**.

**TABLE 1.1.2 - BENCHMARK OF 16-BIT RADIX-4 D.I.T. COMPLEX FFT: AVR32-UC3 OPTIMIZED**

	Optimization	T.F.T.* in SRAM (cycles)		T.F.T.* in FLASH (cycles)		Error		Algorithm's size in memory (bytes) (code size + T.F.T.* size)
		wait-state		wait-state		Amplitude average ( $\times 10^{-5}$ )	Max. amplitude ( $\times 10^{-5}$ )	
		0 at 30MHz	1 at 60MHz	0 at 30MHz	1 at 60MHz			
<b>64-point</b>	(0)	<b>2,611</b> (87.0us)	2,661 ( <b>44.4us</b> )	2,753 (91.8us)	2,877 (48.0us)	3.00	10.04	894 (700 + 194)
	(1)	2,951 (98.4us)	2,999 (50.0us)	3,097 (103.2us)	3,265 (54.4us)	<b>1.63</b>	<b>6.53</b>	774 (580 + 194)
	(2)	2,833 (94.4us)	2,912 (48.5us)	3,027 (100.9us)	3,221 (53.7us)	2.93	10.04	<b>710</b> (644 + 66)
	(3)	3,206 (106.9us)	3,311 (55.2us)	3,458 (115.3us)	3,683 (61.4us)	1.63	6.53	766 (700 + 66)
<b>256-point</b>	(0)	<b>13,661</b> (455.4us)	13,932 ( <b>232.2us</b> )	14,306 (476.9us)	14,904 (248.4us)	2.78	13.86	1.4K (700 + 770)
	(1)	15,777 (525.9us)	16,033 (267.2us)	16,428 (547.6us)	17,242 (287.4us)	<b>1.68</b>	<b>7.46</b>	1.3K (580 + 770)
	(2)	14,651 (488.4us)	15,056 (250.9us)	15,527 (517.6us)	16,442 (274.0us)	2.87	15.82	<b>902</b> (644 + 258)
	(3)	16,916 (563.9us)	17,469 (291.2us)	18,041 (601.4us)	19,152 (319.2us)	1.68	7.46	958 (700 + 258)
<b>1024-point</b>	(0)	<b>67,671</b> (2.26ms)	69,027 ( <b>1.15ms</b> )	70,355 (2.35ms)	73,059 (1.22ms)	2.84	19.33	3.7K (700 + 3K)
	(1)	79,195 (2.64ms)	80,475 (1.34ms)	81,887 (2.73ms)	85,507 (1.43ms)	<b>1.69</b>	<b>10.23</b>	3.6K (580 + 3K)
	(2)	71,765 (2.39ms)	73,680 (1.23ms)	75,403 (2.51ms)	79,423 (1.32ms)	2.86	19.33	<b>1.6K</b> (644 + 1K)
	(3)	83,906 (2.80ms)	86,635 (1.44ms)	88,560 (2.95ms)	93,629 (1.56ms)	1.69	10.23	1.7K (700 + 1K)
<b>4096-point</b>	(0)	<b>322,897</b> (10.76ms)	329,370 ( <b>5.49ms</b> )	333,764 (11.13ms)	345,678 (5.76ms)	2.80	23.69	12.7K (700 + 12K)
	(1)	381,269 (12.71ms)	387,413 (6.46ms)	392,146 (13.07ms)	407,788 (6.80ms)	<b>1.58</b>	<b>11.84</b>	12.6K (580 + 12K)
	(2)	339,439 (11.31ms)	348,176 (5.80ms)	354,159 (11.81ms)	371,396 (6.19ms)	2.81	23.69	<b>4.6K</b> (644 + 4K)
	(3)	400,304 (13.34ms)	413,273 (6.89ms)	419,111 (13.97ms)	441,578 (7.36ms)	1.58	11.84	4.7K (700 + 4K)

\*: Twiddle Factors Table.

(0): Algorithmic optimized for **speed**.

(1): Algorithmic optimized for **accuracy**.

(2): Algorithmic optimized for **size**.

(3): Algorithmic optimized for **size** and **accuracy**.

**TABLE 1.2.1 - BENCHMARK OF 32-BIT RADIX-4 D.I.T. COMPLEX FFT: GENERIC**

	Optimization	T.F.T.* in SRAM (cycles)		T.F.T.* in FLASH (cycles)		Error		Algorithm's size in memory (bytes) (code size + T.F.T.* size)
		wait-state		wait-state		Amplitude average ( $\times 10^{-9}$ )	Max. amplitude ( $\times 10^{-9}$ )	
		0 at 30MHz	1 at 60MHz	0 at 30MHz	1 at 60MHz			
<b>64-point</b>	(0)	<b>13,206</b> (440.2us)	13,509 ( <b>225.2us</b> )	13,580 (452.7us)	14,063 (234.4us)	0.70	5.70	2.2K (1816 + 392)
	(1)	15,323 (510.8us)	15,659 (261.0us)	15,627 (520.9us)	16,113 (268.6us)	<b>0.60</b>	<b>5.70</b>	2.4K (2112 + 392)
	(2)	13,622 (454.1us)	14,011 (233.5us)	13,938 (464.6us)	14,497 (241.6us)	0.70	5.70	<b>2.0K</b> (1952 + 136)
	(3)	15,714 (523.8us)	16,245 (270.8us)	16,058 (535.3us)	16,805 (280.1us)	0.60	5.70	2.3K (2248 + 136)
<b>256-point</b>	(0)	<b>74,297</b> (2.48ms)	75,940 ( <b>1.27ms</b> )	75,992 (2.53ms)	78,445 (1.31ms)	0.50	4.80	3.3K (1816 + 1.5K)
	(1)	87,791 (2.93ms)	89,605 (1.49ms)	89,165 (2.97ms)	91,636 (1.53ms)	<b>0.30</b>	<b>4.80</b>	3.6K (2112 + 1.5K)
	(2)	76,136 (2.54ms)	78,160 (1.30ms)	77,537 (2.58ms)	80,329 (1.34ms)	0.50	4.80	<b>2.4K</b> (1952 + 520)
	(3)	89,543 (2.98ms)	92,446 (1.54ms)	91,058 (3.04ms)	94,978 (1.59ms)	0.30	4.80	2.7K (2248 + 520)
<b>1024-point</b>	(0)	<b>383,212</b> (12.77ms)	391,715 ( <b>6.53ms</b> )	390,260 (13.01ms)	402,123 (6.70ms)	0.50	8.80	7.8K (1816 + 6K)
	(1)	457,571 (15.25ms)	466,815 (7.78ms)	463,279 (15.44ms)	475,223 (7.92ms)	<b>0.30</b>	<b>6.10</b>	8.1K (2112 + 6K)
	(2)	390,794 (13.03ms)	400,869 (6.68ms)	396,576 (13.22ms)	409,841 (6.83ms)	0.50	8.80	<b>3.9K</b> (1952 + 2K)
	(3)	464,988 (15.50ms)	479,847 (8.00ms)	471,226 (15.71ms)	490,367 (8.17ms)	0.30	6.10	4.2K (2248 + 2K)

\*: Twiddle Factors Table.

(0): Algorithmic optimized for **speed**.

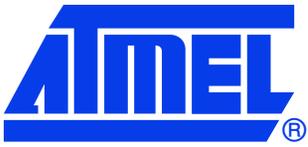
(1): Algorithmic optimized for **accuracy**.

(2): Algorithmic optimized for **size**.

(3): Algorithmic optimized for **size and accuracy**.

**TABLE 2.1.1 - BENCHMARK OF 16-BIT CONVOLUTION: GENERIC**

1 <sup>st</sup> input signal	2 <sup>nd</sup> input signal	Execution time (cycles)		Error	
		wait-state		Amplitude average ( $\times 10^{-5}$ )	Max. amplitude ( $\times 10^{-5}$ )
		0 at 30MHz	1 at 60MHz		
32-point	32-points	15,681 (522.7us)	16,344 (272.4us)	1.60	3.90
	64-points	23,524 (784.1us)	24,508 (408.5us)	2.00	4.50
	128-points	39,204 (1.31ms)	40,830 (680.5us)	1.90	4.50
	256-points	70,564 (2.35ms)	73,470 (1.22ms)	1.70	4.10
64-point	64-points	57,757 (1.93ms)	60,084 (1.00ms)	1.80	4.70
	128-points	86,752 (2.89ms)	90,234 (1.50ms)	1.80	4.40
	256-points	144,736 (4.82ms)	150,522 (2.51ms)	1.50	4.80
128-point	128-points	221,780 (7.39ms)	230,512 (3.84ms)	1.80	5.30
	256-points	333,018 (11.10ms)	346,097 (5.77ms)	1.70	5.00
256-point	256-points	869,316 (28.98ms)	903,136 (15.05ms)	1.70	5.40



**TABLE 2.1.2 - BENCHMARK OF 16-BIT CONVOLUTION: AVR32-UC3 OPTIMIZED**

1 <sup>st</sup> input signal	2 <sup>nd</sup> input signal	Execution time (cycles)		Error	
		wait-state		Amplitude average ( $\times 10^{-5}$ )	Max. amplitude ( $\times 10^{-5}$ )
		0 at 30MHz	1 at 60MHz		
32-point	32-points	5,571 (185.7us)	6,127 (102.1us)	1.60	3.90
	64-points	8,248 (274.9us)	9,070 (151.2us)	2.00	4.50
	128-points	13,592 (453.1us)	14,944 (249.1us)	1.90	4.50
	256-points	24,280 (809.3us)	26,688 (444.8us)	1.70	4.10
64-point	64-points	19,087 (636.2us)	20,947 (349.1us)	1.80	4.70
	128-points	28,532 (951.1us)	31,308 (521.8us)	1.80	4.40
	256-points	47,412 (1.58ms)	52,012 (866.9us)	1.50	4.80
128-point	128-points	70,694 (2.36ms)	77,471 (1.29ms)	1.80	5.30
	256-points	105,966 (3.53ms)	116,099 (1.93ms)	1.70	5.00
256-point	256-points	272,214 (9.07ms)	298,031 (4.97ms)	1.70	5.40

**TABLE 2.2.1 - BENCHMARK OF 32-BIT CONVOLUTION: GENERIC**

1 <sup>st</sup> input signal	2 <sup>nd</sup> input signal	Execution time (cycles)		Error	
		wait-state		Amplitude average ( $\times 10^{-9}$ )	Max. amplitude ( $\times 10^{-9}$ )
		0 at 30MHz	1 at 60MHz		
32-point	32-points	28,359 (945.3us)	29,182 (486.4us)	0.40	1.60
	64-points	42,572 (1.42ms)	43,788 (729.8us)	0.40	2.10
	128-points	70,988 (2.37ms)	72,990 (1.22ms)	0.30	1.90
	256-points	127,820 (4.26ms)	131,390 (2.19ms)	0.40	1.70
64-point	64-points	109,179 (3.64ms)	112,334 (1.87ms)	0.40	1.70
	128-points	163,968 (5.47ms)	168,678 (2.81ms)	0.50	1.60
	256-points	273,536 (9.12ms)	281,350 (4.69ms)	0.60	2.70
128-point	128-points	429,026 (14.30ms)	441,458 (7.36ms)	0.40	2.30
	256-points	644,074 (21.47ms)	662,677 (11.04ms)	0.40	2.00
256-point	256-points	1,701,554 (56.72ms)	1,750,962 (29.18ms)	0.50	3.10

**TABLE 2.2.2 - BENCHMARK OF 32-BIT CONVOLUTION: AVR32-UC3 OPTIMIZED**

1 <sup>st</sup> input signal	2 <sup>nd</sup> input signal	Execution time (cycles)		Error	
		wait-state		Amplitude average ( $\times 10^{-9}$ )	Max. amplitude ( $\times 10^{-9}$ )
		0 at 30MHz	1 at 60MHz		
32-point	32-points	13,361 (445.4us)	13,680 (228.0us)	0.60	2.30
	64-points	19,958 (665.3us)	20,414 (340.2us)	0.50	2.10
	128-points	33,142 (1.10ms)	33,872 (564.5us)	0.50	1.90
	256-points	59,510 (1.98ms)	60,784 (1.01ms)	0.50	2.10
64-point	64-points	50,501 (1.68ms)	51,624 (860.4us)	0.50	1.70
	128-points	75,722 (2.52ms)	77,376 (1.29ms)	0.60	2.40
	256-points	126,154 (4.21ms)	128,864 (2.15ms)	0.70	2.70
128-point	128-points	196,972 (6.57ms)	201,244 (3.35ms)	0.50	2.30
	256-points	295,540 (9.85ms)	301,887 (5.03ms)	0.60	2.30
256-point	256-points	778,684 (25.96ms)	795,388 (13.26ms)	0.60	3.10

**TABLE 3.1.1 - BENCHMARK OF 16-BIT FIR FILTER: GENERIC**

	Number of Taps	I.R.* in SRAM (cycles)		I.R.* in FLASH (cycles)		Error	
		wait-state		wait-state		Amplitude average ( $\times 10^{-5}$ )	Max. amplitude ( $\times 10^{-5}$ )
		0 at 30MHz	1 at 60MHz	0 at 30MHz	1 at 60MHz		
<b>64-point</b>	24	<b>7,424</b> (247.5us)	7,682 ( <b>128.0us</b> )	10,704 (356.8us)	12,352 (205.9us)	2.27	9.46
	48	<b>5,780</b> (192.7us)	5,996 ( <b>99.9us</b> )	8,517 (283.9us)	9,868 (164.5us)	3.09	15.57
<b>256-point</b>	24	<b>41,793</b> (1.39ms)	43,202 ( <b>720.0us</b> )	60,433 (2.01ms)	69,760 (1.16ms)	2.22	9.46
	48	<b>70,101</b> (2.34ms)	72,620 ( <b>1.21ms</b> )	103,750 (3.46ms)	120,268 (2.00ms)	5.66	27.20
	72	<b>90,921</b> (3.03ms)	94,262 ( <b>1.57ms</b> )	135,691 (4.52ms)	157,528 (2.63ms)	11.25	52.65
	100	<b>105,127</b> (3.50ms)	108,903 ( <b>1.82ms</b> )	156,466 (5.22ms)	185,989 (3.10ms)	14.19	63.71
<b>512-point</b>	24	<b>87,617</b> (2.92ms)	90,562 ( <b>1.51ms</b> )	126,737 (4.22ms)	146,304 (2.44ms)	2.23	9.46
	48	<b>155,861</b> (5.20ms)	161,452 ( <b>2.69ms</b> )	230,726 (7.69ms)	267,468 (4.46ms)	5.78	27.20
	72	<b>216,617</b> (7.22ms)	224,566 ( <b>3.74ms</b> )	323,339 (10.78ms)	375,384 (6.26ms)	10.79	52.65
	100	<b>276,391</b> (9.21ms)	286,311 ( <b>4.77ms</b> )	411,442 (13.71ms)	489,093 (8.15ms)	14.05	63.71
<b>1024-point</b>	24	<b>179,265</b> (5.98ms)	185,282 ( <b>3.09ms</b> )	259,345 (8.64ms)	299,392 (4.99ms)	2.21	9.46
	48	<b>327,381</b> (10.91ms)	339,116 ( <b>5.65ms</b> )	484,678 (16.16ms)	561,868 (9.36ms)	5.85	27.20
	72	<b>468,009</b> (15.60ms)	485,174 ( <b>8.09ms</b> )	698,635 (23.29ms)	811,096 (13.52ms)	10.69	52.65
	100	<b>618,919</b> (20.63ms)	641,127 ( <b>10.69ms</b> )	921,394 (30.71ms)	1,095,301 (18.26ms)	13.99	63.71

\*: Impulse Response.

**TABLE 3.1.2 - BENCHMARK OF 16-BIT FIR FILTER: AVR32-UC3 OPTIMIZED**

	Number of Taps	I.R.* in SRAM (cycles)		I.R.* in FLASH (cycles)		Error	
		wait-state		wait-state		Amplitude average ( $\times 10^{-5}$ )	Max. amplitude ( $\times 10^{-5}$ )
		0 at 30MHz	1 at 60MHz	0 at 30MHz	1 at 60MHz		
<b>64-point</b>	24	<b>2,439</b> (81.3us)	2,657 ( <b>44.3us</b> )	2,703 (90.1us)	3,054 (50.9us)	2.27	9.46
	48	<b>2,115</b> (70.5us)	2,309 ( <b>38.5us</b> )	2,355 (78.5us)	2,670 (44.5us)	3.09	15.57
<b>256-point</b>	24	<b>12,712</b> (423.7us)	13,841 ( <b>230.7us</b> )	14,128 (470.9us)	15,966 (266.1us)	2.22	9.46
	48	<b>21,604</b> (720.1us)	23,573 ( <b>392.9us</b> )	24,148 (804.9us)	27,390 (456.5us)	5.66	27.20
	72	<b>28,192</b> (939.7us)	30,785 ( <b>513.1us</b> )	31,576 (1.05ms)	35,862 (597.7us)	11.25	52.65
	100	<b>32,966</b> (1.10ms)	36,014 ( <b>600.2us</b> )	36,966 (1.23ms)	42,015 (700.3us)	14.19	63.71
<b>512-point</b>	24	<b>26,408</b> (880.3us)	28,753 ( <b>479.2us</b> )	29,360 (978.7us)	33,182 (553.0us)	2.23	9.46
	48	<b>47,588</b> (1.59ms)	51,925 ( <b>865.4us</b> )	53,204 (1.77ms)	60,350 (1.01ms)	5.78	27.20
	72	<b>66,464</b> (2.22ms)	72,577 ( <b>1.21ms</b> )	74,456 (2.48ms)	84,566 (1.41ms)	10.79	52.65
	100	<b>85,574</b> (2.85ms)	93,486 ( <b>1.56ms</b> )	95,974 (3.20ms)	109,087 (1.82ms)	14.05	63.71
<b>1024-point</b>	24	<b>53,800</b> (1.79ms)	58,577 ( <b>976.3us</b> )	59,824 (1.99ms)	67,614 (1.13ms)	2.21	9.46
	48	<b>99,556</b> (3.32ms)	108,629 ( <b>1.81ms</b> )	111,316 (3.71ms)	126,270 (2.10ms)	5.85	27.20
	72	<b>143,008</b> (4.77ms)	156,161 ( <b>2.60ms</b> )	160,216 (5.34ms)	181,974 (3.03ms)	10.69	52.65
	100	<b>190,790</b> (6.36ms)	208,430 ( <b>3.47ms</b> )	213,990 (7.13ms)	243,231 (4.05ms)	13.99	63.71

\*: Impulse Response.

**TABLE 3.2.1 - BENCHMARK OF 32-BIT FIR FILTER: GENERIC**

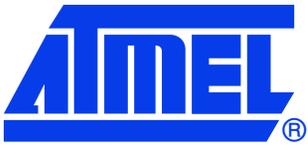
	Number of Taps	I.R.* in SRAM (cycles)		I.R.* in FLASH (cycles)		Error	
		wait-state		wait-state		Amplitude average ( $\times 10^{-9}$ )	Max. amplitude ( $\times 10^{-9}$ )
		0 at 30MHz	1 at 60MHz	0 at 30MHz	1 at 60MHz		
<b>64-point</b>	24	<b>13,984</b> (466.1us)	14,365 ( <b>239.4us</b> )	16,608 (553.6us)	18,624 (310.4us)	2.10	12.40
	48	<b>11,101</b> (370.0us)	11,419 ( <b>190.3us</b> )	13,311 (443.7us)	14,865 (247.8us)	2.50	14.40
<b>256-point</b>	24	<b>79,073</b> (2.64ms)	81,181 ( <b>1.35ms</b> )	93,985 (3.13ms)	105,408 (1.76ms)	2.30	17.40
	48	<b>135,518</b> (4.52ms)	139,291 ( <b>2.32ms</b> )	162,688 (5.42ms)	181,713 (3.03ms)	2.70	16.60
	72	<b>177,131</b> (5.90ms)	182,137 ( <b>3.04ms</b> )	213,391 (7.11ms)	238,002 (3.97ms)	4.60	31.50
	100	<b>187,238</b> (6.24ms)	194,313 ( <b>3.24ms</b> )	241,717 (8.06ms)	264,808 (4.41ms)	4.60	31.90
<b>512-point</b>	24	<b>165,857</b> (5.53ms)	170,269 ( <b>2.84ms</b> )	197,153 (6.57ms)	221,120 (3.69ms)	2.60	23.10
	48	<b>301,406</b> (10.05ms)	309,787 ( <b>5.16ms</b> )	361,856 (12.06ms)	404,177 (6.74ms)	3.20	23.90
	72	<b>422,123</b> (14.07ms)	434,041 ( <b>7.23ms</b> )	508,559 (16.95ms)	567,218 (9.45ms)	5.10	35.30
	100	<b>492,390</b> (16.41ms)	510,985 ( <b>8.52ms</b> )	635,701 (21.19ms)	696,424 (11.61ms)	5.10	31.90
<b>1024-point</b>	24	<b>339,425</b> (11.31ms)	348,445 ( <b>5.81ms</b> )	403,489 (13.45ms)	452,544 (7.54ms)	3.70	28.40
	48	<b>633,182</b> (21.11ms)	650,779 ( <b>10.85ms</b> )	760,192 (25.34ms)	849,105 (14.15ms)	4.60	29.30
	72	<b>912,107</b> (30.40ms)	937,849 ( <b>15.63ms</b> )	1,098,895 (36.63ms)	1,225,650 (20.43ms)	6.50	35.30
	100	<b>1,102,694</b> (36.76ms)	1,144,329 ( <b>19.07ms</b> )	1,423,669 (47.46ms)	1,559,656 (26.00ms)	6.40	33.30

\*: Impulse Response.

**TABLE 3.2.2 - BENCHMARK OF 32-BIT FIR FILTER: AVR32-UC3 OPTIMIZED**

	Number of Taps	I.R.* in SRAM (cycles)		I.R.* in FLASH (cycles)		Error	
		wait-state		wait-state		Amplitude average ( $\times 10^{-9}$ )	Max. amplitude ( $\times 10^{-9}$ )
		0 at 30MHz	1 at 60MHz	0 at 30MHz	1 at 60MHz		
<b>64-point</b>	24	<b>6,479</b> (216.0us)	6,613 ( <b>110.2us</b> )	9,141 (304.7us)	10,918 (182.0us)	2.10	12.40
	48	<b>5,132</b> (171.1us)	5,245 ( <b>87.4us</b> )	7,305 (243.5us)	8,866 (147.8us)	2.50	14.40
<b>256-point</b>	24	<b>36,432</b> (1.21ms)	37,140 ( <b>619.0us</b> )	51,574 (1.72ms)	61,605 (1.03ms)	2.30	12.40
	48	<b>62,157</b> (2.07ms)	63,420 ( <b>1.06ms</b> )	88,906 (2.96ms)	107,937 (1.80ms)	2.70	16.60
	72	<b>81,114</b> (2.70ms)	82,788 ( <b>1.38ms</b> )	116,446 (3.88ms)	142,173 (2.37ms)	4.60	31.50
	100	<b>94,441</b> (3.15ms)	96,490 ( <b>1.61ms</b> )	140,910 (4.70ms)	166,671 (2.78ms)	4.60	31.90
<b>512-point</b>	24	<b>76,368</b> (2.55ms)	77,844 ( <b>1.30ms</b> )	108,150 (3.61ms)	129,189 (2.15ms)	2.60	23.10
	48	<b>138,189</b> (4.61ms)	140,988 ( <b>2.35ms</b> )	197,706 (6.59ms)	240,033 (4.00ms)	3.20	23.90
	72	<b>193,242</b> (6.44ms)	197,220 ( <b>3.29ms</b> )	277,470 (9.25ms)	338,781 (5.65ms)	5.10	35.30
	100	<b>248,297</b> (8.28ms)	253,674 ( <b>4.23ms</b> )	370,542 (12.35ms)	438,287 (7.30ms)	5.10	31.90
<b>1024-point</b>	24	<b>156,240</b> (5.21ms)	159,252 ( <b>2.65ms</b> )	221,302 (7.38ms)	264,357 (4.41ms)	3.70	28.40
	48	<b>290,253</b> (9.68ms)	296,124 ( <b>4.94ms</b> )	415,306 (13.84ms)	504,225 (8.40ms)	4.50	29.30
	72	<b>417,498</b> (13.92ms)	426,084 ( <b>7.10ms</b> )	599,518 (19.99ms)	731,997 (12.20ms)	6.50	35.30
	100	<b>556,009</b> (18.53ms)	568,042 ( <b>9.47ms</b> )	829,806 (27.66ms)	981,519 (16.36ms)	6.40	33.30

\*: Impulse Response.



**TABLE 4.1.1 - BENCHMARK OF 16-BIT FIR FILTER: GENERIC**

	Order of the filter	Execution time (cycles)		Error	
		wait-state		Amplitude average ( $\times 10^{-5}$ )	Max. amplitude ( $\times 10^{-5}$ )
		0 at 30MHz	1 at 60MHz		
72-point	2	5,294 (176.5us)	5,717 ( <b>95.3us</b> )	1.50	4.00
	7	11,469 (382.3us)	12,802 ( <b>213.4us</b> )	1.40	4.30
	12	16,319 (544.0us)	18,387 ( <b>306.5us</b> )	2.50	7.60
256-point	2	19,096 (636.5us)	20,621 ( <b>343.7us</b> )	1.50	4.00
	7	44,591 (1.49ms)	49,786 ( <b>829.8us</b> )	1.40	4.30
	12	68,761 (2.29ms)	77,451 ( <b>1.29ms</b> )	3.50	8.90
512-point	2	38,296 (1.28ms)	41,357 ( <b>689.3us</b> )	1.50	4.00
	7	90,671 (3.02ms)	101,242 ( <b>1.69ms</b> )	1.40	4.30
	12	141,721 (4.72ms)	159,627 ( <b>2.66ms</b> )	3.70	8.90
1024-point	2	76,696 (2.56ms)	82,829 ( <b>1.38ms</b> )	1.50	4.00
	7	182,831 (6.09ms)	204,154 ( <b>3.40ms</b> )	1.40	4.30
	12	287,641 (9.59ms)	323,979 ( <b>5.40ms</b> )	3.90	8.90

**TABLE 4.1.2 - BENCHMARK OF 16-BIT FIR FILTER: AVR32-UC3 OPTIMIZED**

	Order of the filter	Execution time (cycles)		Error	
		wait-state		Amplitude average ( $\times 10^{-5}$ )	Max. amplitude ( $\times 10^{-5}$ )
		0 at 30MHz	1 at 60MHz		
72-point	2	<b>2,725</b> (90.8us)	2,871 ( <b>47.9us</b> )	1.20	4.00
	7	<b>4,332</b> (144.4us)	4,682 ( <b>78.0us</b> )	1.90	6.90
	12	<b>6,089</b> (203.0us)	6,534 ( <b>108.9us</b> )	3.30	8.40
256-point	2	<b>9,167</b> (305.6us)	9,633 ( <b>160.6us</b> )	1.10	4.00
	7	<b>15,006</b> (500.2us)	16,228 ( <b>270.5us</b> )	1.70	6.90
	12	<b>22,283</b> (742.8us)	23,876 ( <b>397.9us</b> )	5.10	12.40
512-point	2	<b>18,127</b> (604.2us)	19,041 ( <b>317.4us</b> )	1.10	4.00
	7	<b>29,854</b> (995.1us)	32,292 ( <b>538.2us</b> )	1.70	6.90
	12	<b>44,811</b> (1.49ms)	48,004 ( <b>800.1us</b> )	5.60	12.40
1024-point	2	<b>36,047</b> (1.20ms)	37,857 ( <b>631.0us</b> )	1.10	4.00
	7	<b>59,550</b> (1.99ms)	64,420 ( <b>1.07ms</b> )	1.70	6.90
	12	<b>89,867</b> (3.00ms)	96,260 ( <b>1.60ms</b> )	5.80	12.40

**TABLE 4.2.2 - BENCHMARK OF 32-BIT FIR FILTER: GENERIC**

	Order of the filter	Execution time (cycles)		Error	
		wait-state		Amplitude average ( $\times 10^{-9}$ )	Max. amplitude ( $\times 10^{-9}$ )
		0 at 30MHz	1 at 60MHz		
72-point	2	<b>7,582</b> (252.7us)	8,072 ( <b>134.5us</b> )	1.00	3.80
	7	<b>14,517</b> (483.9us)	15,922 ( <b>265.4us</b> )	1.50	7.00
	12	<b>19,952</b> (665.1us)	22,097 ( <b>368.3us</b> )	2.60	10.30
256-point	2	<b>27,456</b> (915.2us)	29,232 ( <b>487.2us</b> )	0.80	3.80
	7	<b>56,471</b> (1.88ms)	61,922 ( <b>1.03ms</b> )	1.50	7.00
	12	<b>83,986</b> (2.80ms)	92,937 ( <b>1.55ms</b> )	1.50	10.30
512-point	2	<b>55,104</b> (1.84ms)	58,672 ( <b>977.9us</b> )	0.80	3.80
	7	<b>114,839</b> (3.83ms)	125,922 ( <b>2.10ms</b> )	1.50	7.00
	12	<b>173,074</b> (5.77ms)	191,497 ( <b>3.19ms</b> )	1.40	10.30
1024-point	2	<b>110,400</b> (3.68ms)	117,552 ( <b>1.96ms</b> )	0.80	3.80
	7	<b>231,575</b> (7.72ms)	253,922 ( <b>4.23ms</b> )	1.50	7.00
	12	<b>351,250</b> (11.71ms)	388,617 ( <b>6.48ms</b> )	1.30	10.30

**TABLE 4.2.1 - BENCHMARK OF 32-BIT FIR FILTER: AVR32-UC3 OPTIMIZED**

	Order of the filter	Execution time (cycles)		Error	
		wait-state		Amplitude average ( $\times 10^{-9}$ )	Max. amplitude ( $\times 10^{-9}$ )
		0 at 30MHz	1 at 60MHz		
72-point	2	5,297 (176.6us)	5,662 (94.4us)	1.00	3.80
	7	8,859 (295.3us)	9,233 (153.9us)	1.50	7.00
	12	11,670 (389.0us)	12,239 (204.0us)	3.00	10.30
256-point	2	18,731 (624.4us)	20,014 (333.6us)	0.80	3.80
	7	33,333 (1.11ms)	34,625 (577.1us)	1.50	7.00
	12	46,816 (1.56ms)	48,855 (814.3us)	1.80	10.30
512-point	2	37,419 (1.25ms)	39,982 (666.4us)	0.80	3.80
	7	67,381 (2.25ms)	69,953 (1.17ms)	1.60	7.00
	12	95,712 (3.19ms)	99,799 (1.66ms)	1.70	10.30
1024-point	2	74,795 (2.49ms)	79,918 (1.33ms)	0.80	3.80
	7	135,477 (4.52ms)	140,609 (2.34ms)	1.60	7.00
	12	193,504 (6.45ms)	201,687 (3.36ms)	1.60	10.30

## 6 Comparative

### 6.1 16-bit complex FFT

#### STMicroelectronics ARM9E-based STR91x

	Cycle count	at 96 MHz	at 60 MHz	at 30MHz
<b>64-point</b>	2,701	28.14 us	45.02 us	90.03 us
<b>256-point</b>	13,740	143.12 us	229.00 us	458.00 us
<b>1024-point</b>	68,534	713.90 us	1.14 ms	2.28 ms

#### Microchip dsPIC

	Cycle count	at 40 MHz	at 30 MHz
<b>64-point</b>	3,739	93.5 us	124.63 us
<b>256-point</b>	19,055	476.4 us	635.17 us

### 6.2 16-bit FIR Filter

#### STMicroelectronics ARM9E-based STR91x

STMicroelectronics uses another algorithm to compute its FIR Filter. It is not comparable because it is made to compute a signal in real-time while ours compute a whole block of data and so is not optimized the same way as ours.

Comparatively, to compute a 24-TAP filter of a signal of 64 points, ST algorithm would take approximately  $1,813 * (64 - 24 + 1) = 74,333$  cycles, while ours takes only 2,439 cycles.

#### Microchip dsPIC

Contrariwise to STMicroelectronics, Microchip uses the same algorithm as ours. For the same result, it takes about 33% cycles less than ours. Indeed, the FIR algorithm is based on the “MAC” instruction and dsPIC owns a very efficient one.

In only one cycle, this instruction can read two 16-bits data from memory, update the memory pointers and perform a MAC instruction.

(cf. “Microchip dsPIC – Section 2. - Instruction Set Details” page 35)

<http://ww1.microchip.com/downloads/en/DeviceDoc/sect2.pdf>

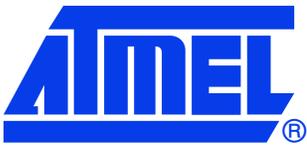
### 6.3 16-bit IIR Filter

#### STMicroelectronics ARM9E-based STR91x

The following results are for a 4<sup>th</sup> order filter.

Number of Taps	Cycle count	at 96 MHz	at 60 MHz	at 30MHz
<b>24-tap</b>	2,248	23.42 us	37.47 us	74.94 us
<b>48-tap</b>	4,396	45.79 us	73.27 us	146.54 us
<b>72-tap</b>	6,544	68.16 us	109.07 us	218.14 us

#### Microchip dsPIC



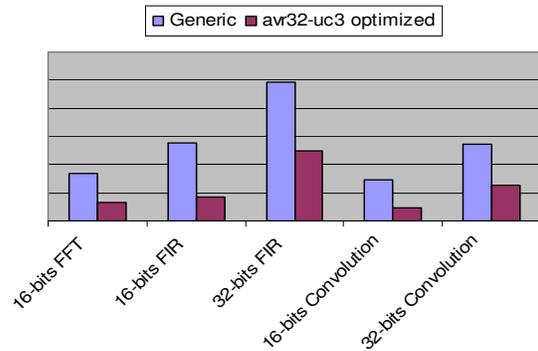
Formula:  $46+N*(16+7*M)$  where M is the order of the filter and N the number of points to process.

### Advantages of the AVR32-DSPLib compared to the others:

- ❖ It can use any fixed-point Q-Formatted numbers.
- ❖ It is compatible with any platforms that are supported by GCC and IAR.
- ❖ It can be customized with several algorithm optimization options according to your needs.

### Code optimization with DSP Instructions:

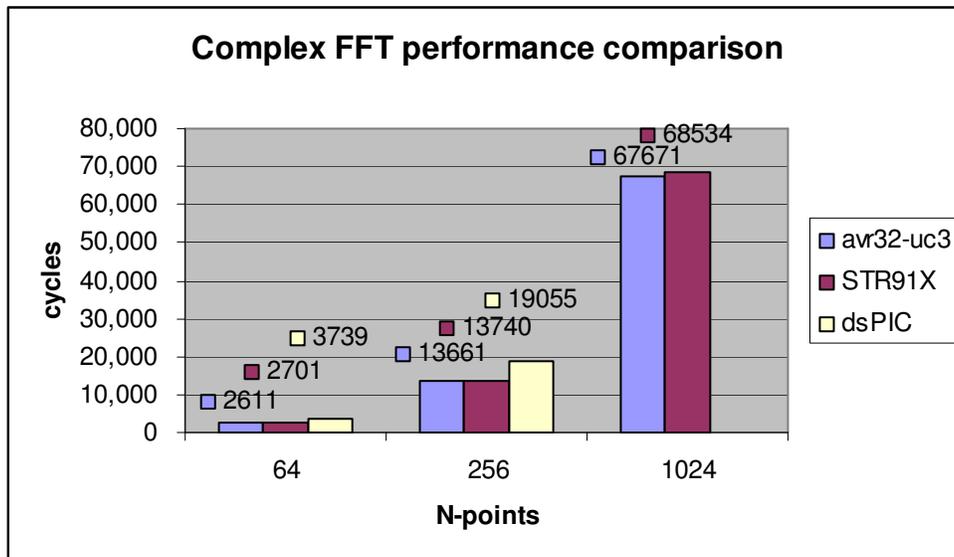
This graphics shows the difference between the code optimized with DSP Instructions for the avr32-uc3 (■ avr32 uc3 optimized) and the code without (■ generic). On the avr32-uc3, we gain from 100% to 200% of speed execution.



### List of currently implemented functions:

Complex FFT, FIR filter, convolution, partial convolution, sine/cosine, sinusoidal/cosinusoidal generator, vector copy, zero padding.

### Performance comparison:



## IIR Filter performance comparison

